

科目：訊號與系統 適用：電機所系統組

編號：432

考生注意：

1. 依次序作答，只要標明題號，不必抄題。
2. 答案必須寫在答案卷上，否則不予計分。
3. 限用藍、黑色筆作答；試題須隨卷繳回。

本 試 題
共 2 頁
第 1 頁

1. The autocorrelation of a real signal $x(t)$ is defined as

$$r_{xx}(t) = \int_{-\infty}^{\infty} x(\tau)x(\tau-t)d\tau$$

Evaluate the autocorrelation of the following signals:

- (a) (5%) $x(t) = e^{-t}u(t)$
 - (b) (5%) $x(t) = \cos(\pi t)[u(t+1) - u(t-1)]$
 - (c) (5%) $x(t) = u(t) - 2u(t-1) + u(t-2)$
 - (d) (5%) $x(t) = u(t-a) - u(t-a-1)$
2. A linear system H has the input-output pairs depicted in Fig. P2(a). Answer the following questions, and explain your answers.

- (a) (5%) Could this system be causal?
- (b) (5%) Could this system be time-invariant?
- (c) (5%) Could this system be memoryless?
- (d) (5%) What is the output for the input depicted in Fig. P2(b)?

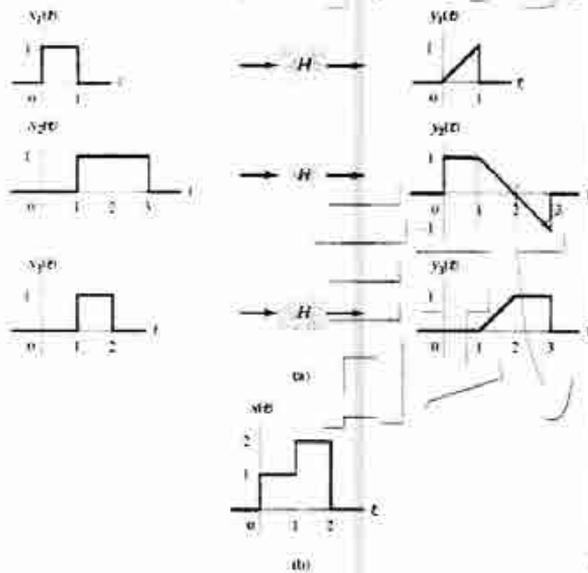


Figure P2.

3. Determine the inverse continuous-time Fourier Transform for the following signals

(a) (5%) $X(j\omega) = \frac{j\omega - 2}{-\omega^2 + 5j\omega + 4}$

(b) (5%) $X(j\omega) = \frac{j\omega + 3}{(j\omega + 1)^2}$

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本 試 題
共 3 頁
第 2 頁

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4. Determine the inverse discrete-time Fourier Transform for the following signals

(a) (5%) $X(e^{j\omega}) = \frac{2e^{-j\omega}}{-\frac{1}{4}e^{-j2\omega} + 1}$

(b) (5%) $X(e^{j\omega}) = \frac{6 - \frac{1}{3}e^{-j\omega} - \frac{1}{3}e^{-j2\omega}}{1 + \frac{1}{4}e^{-j\omega} - \frac{1}{4}e^{-j2\omega}}$

5. For each of the following signals, sampled with sampling interval T_s , determine the bounds on T_s , which guarantee that there will be no aliasing:

(a) (5%) $x(t) = \frac{\sin(3\pi t)}{t} + \cos(2\pi t)$

(b) (5%) $x(t) = \cos(12\pi t) \frac{\sin(\pi t)}{2t}$

6. Given the z -transform pair $x[n] \leftrightarrow \frac{z^3}{z^2 - 16}$, with ROC $|z| < 4$, determine the z -transform of the following signals:

(a) (5%) $y[n] = nx[n]$

(b) (5%) $y[n] = x[n] * x[n-3]$ (* linear convolution)

7. Determine the time-domain signal corresponding to the following z -transforms:

(a) (5%) $X(z) = \cos(z^{-1}), |z| > 0$

(b) (5%) $X(z) = \ln(1 + z^{-1}), |z| > 0$

8. (10%) Determine the transfer function $H(z) = Y(z)/X(z)$ of the system depicted in Fig P8.

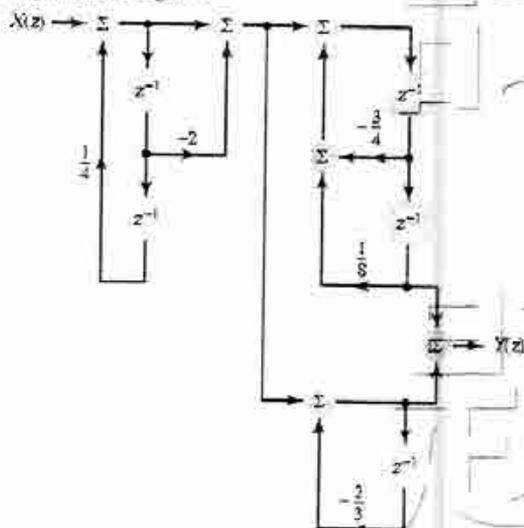


Figure P8